

Robust Network Design with Several Traffic Scenarios

Models and Algorithms

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Michael Jünger³ Frauke Liers² Andrea Lodi¹ Tiziano Parriani¹
Daniel R. Schmidt³

¹DEIS, Università di Bologna

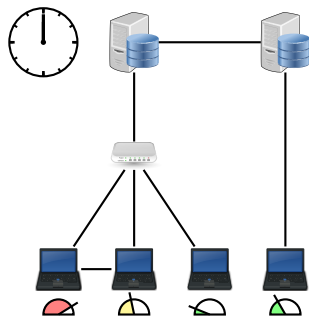
²Department Mathematik, Universität Erlangen-Nürnberg

³Institut für Informatik, Universität zu Köln

Outline

- 1 A Robust Network Design Model
- 2 A Large Neighborhood Search Heuristic
- 3 A Branch-and-Cut Algorithm

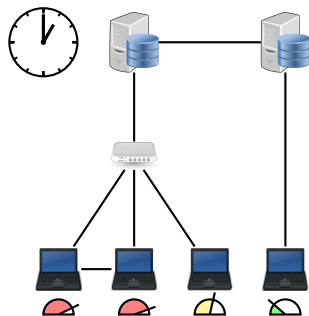
Motivation: A simple model for RND



Model [Buchheim, Liers, Sanità 2011]

- servers with identical data (“supply”)
- users request data (“demand”)
- all servers may answer user requests
- approximate demands by samples during the day
- use samples to design minimum cost network

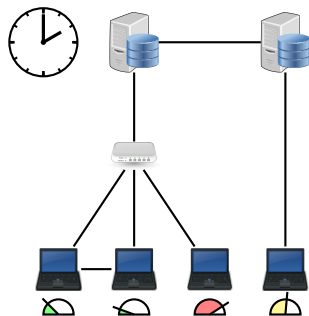
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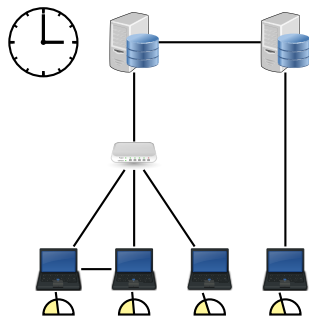
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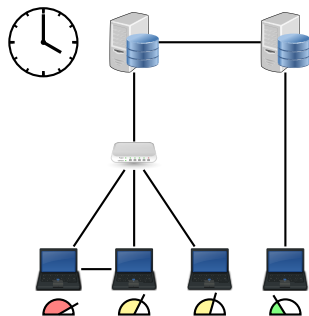
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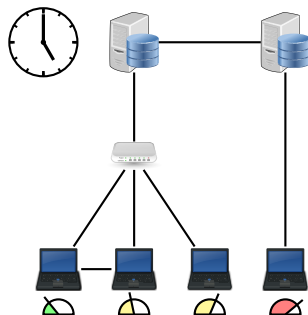
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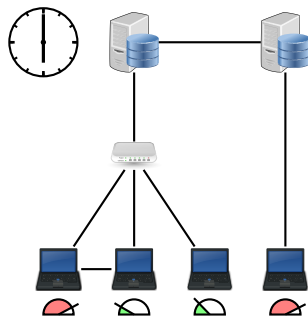
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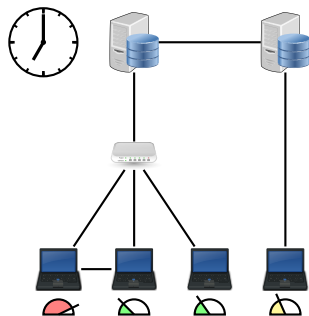
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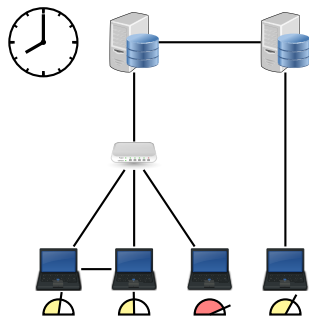
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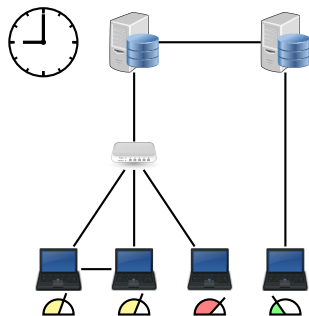
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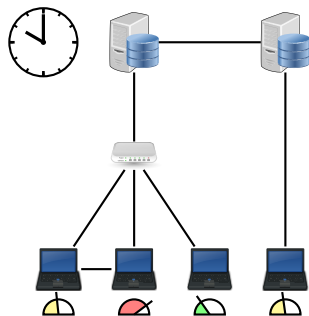
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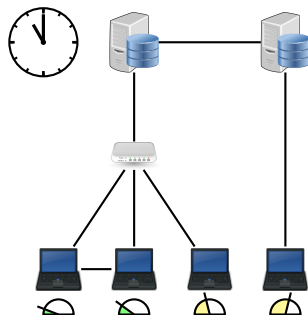
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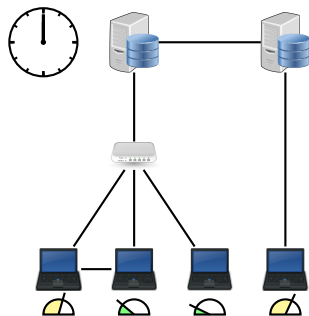
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Single Commodity Robust Network Design

Given:

- undirected graph $G = (V, E)$
- cost vector $c : E \rightarrow \mathbb{Z}_{\geq 0}$
- K integer balance vectors $b_1, \dots, b_K : V \rightarrow \mathbb{Z}$ (“scenarios”)

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Task:

- find integer capacities $u : E \rightarrow \mathbb{Z}_{\geq 0}$
- s.t. there is directed b_i -flow f^i w.r.t. u for all $i = 1, \dots, K$.

$$(1) \quad f_{u,v}^i + f_{v,u}^i \leq u_{u,v} \quad \text{for all } \{u, v\} \in E$$

$$(2) \quad \sum_{u \in \delta(v)} (f_{u,v}^i - f_{v,u}^i) = b_v^i \quad \text{for all } v \in V$$

- minimize $c^T u$

Flow based IP-formulation

$$\min \sum_{\{i,j\} \in E} c_{i,j} u_{i,j}$$

$$f_{i,j}^q + f_{i,j}^q \leq u_{i,j} \quad \text{for all } \{i,j\} \in E, q = 1, \dots, K$$

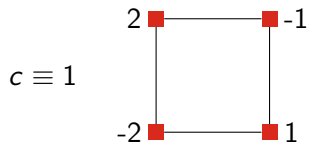
$$\sum_{j \in \delta(i)} (f_{i,j}^q - f_{j,i}^q) = b_i^q \quad \text{for all } i \in V, q = 1, \dots, K$$

$$u_{i,j} \in \mathbb{Z}_{\geq 0} \quad \text{for all } \{i,j\} \in E$$

$$f_{i,j}^q, f_{j,i}^q \in \mathbb{Z}_{\geq 0} \quad \text{for all } \{i,j\} \in E, q = 1, \dots, K$$

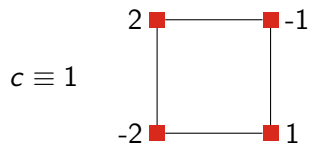
Example (unit edge costs)

Scenario 1

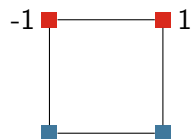


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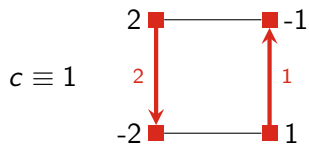


Scenario 2

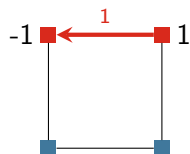


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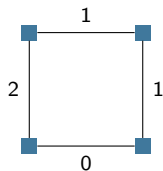
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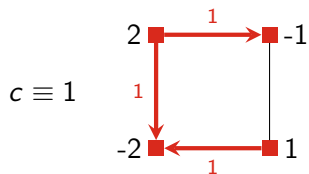
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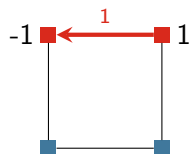
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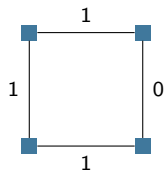
Scenario 1



Scenario 2



Feasible solution:



cost: 3

Heuristic: Improvement Phase

Large Neighborhood Search

- improve feasible solution u^*
- for some $T \geq 0$, search T -neighborhood of u^*
- ➡ shift up to T units of capacity

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Algorithm

- 1 Construct feasible solution u^*
- 2 Remove all edges e with $u^* = 0$
- 3 Solve IP on reduced graph $G = (V, \bar{E})$

Improvement phase IP

$$\min \sum_{\{i,j\} \in \bar{E}} c_{ij} u_{ij}$$

$$\text{s.t.} \quad \sum_{j \in \delta(i)} (f_{ij}^q - f_{ji}^q) = b_i^q \quad \forall i \in V, q = 1, \dots, K$$

$$f_{ij}^q + f_{ji}^q \leq u_{ij} \quad \forall \{i,j\} \in \bar{E}, q = 1, \dots, K$$

$$u_{ij} \leq u_{ij}^* + w_{ij} \quad \forall \{i,j\} \in \bar{E}$$

$$\sum_{\{i,j\} \in \bar{E}} w_{ij} \leq T$$

$$u \in \mathbb{Z}_{\geq 0}^{\bar{E}}, f \geq 0, w \geq 0$$

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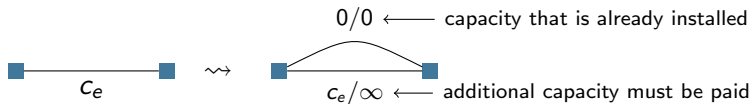
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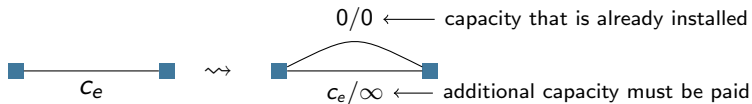
Heuristic: Constructive Phase

- 1 insert auxilliary edge (for all edges $e \in E$)



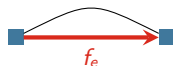
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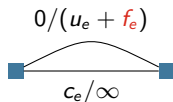


- 2 For $q = 1, \dots, K$:

- 1 compute MinCost flow for q -th scenario

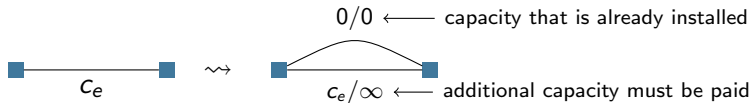


- 2 update capacities for subsequent scenarios



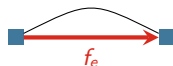
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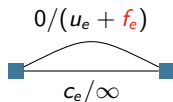


- 2 For $q = 1, \dots, K$: **Caution: The order matters!**

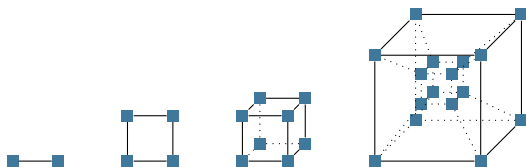
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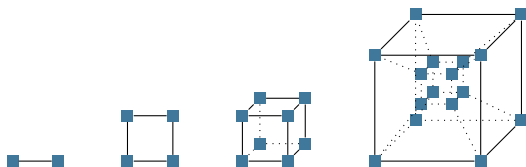
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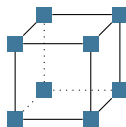
Class of difficult instances: hypercubes



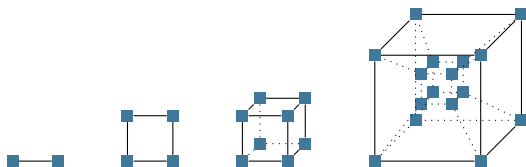
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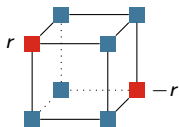
- Scenarios: Opposite nodes get balance of $\pm r$



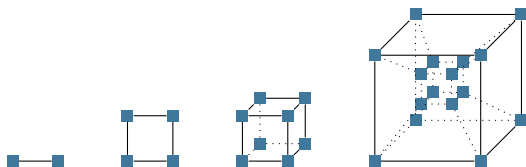
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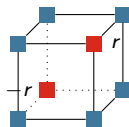
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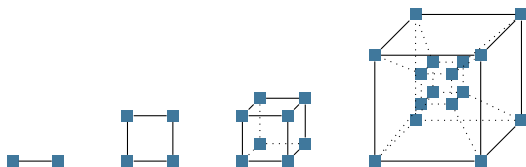
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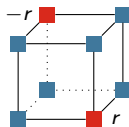
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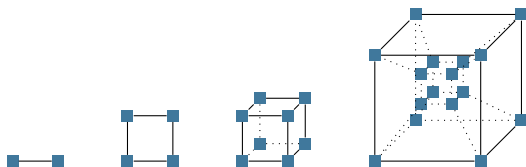
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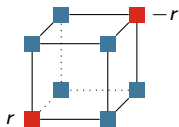
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Integrality gap on hypercubes

Ratio of best integer and best fractional solution

$$\text{GAP}(I) := \frac{\text{OPT}_{\text{int}}(I)}{\text{OPT}_{\text{frac}}(I)}$$

We can prove...

- $r = 1$: $\text{GAP}(I)$ converges to 2 as $d \rightarrow \infty$
- $r > 1$: $\text{GAP}(I)$ is 1 for all $d > 2$

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Observe

$$OPT_{frac} = r \cdot 2^{d-1}$$

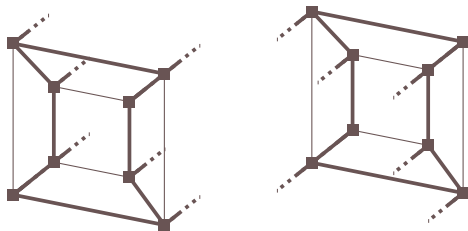
Analyze support of opt. int. solution

- Any connected component contains $\geq 2d$ nodes
- \Rightarrow at most $2^d/(2d)$ connected components
- \Rightarrow solution contains at least $2^d - 2^d/(2d)$ edges
- $GAP(I, d) \geq 2 - 1/d$

$r > 1$: $GAP(I)$ is 1 for all $d > 2$

Building large demands from smaller ones

- $r = 2$ and $d > 1$: costs $2^d = 2 \cdot 2^{d-1}$ (Hamiltonian cycle)
- $r = 3$ and $d > 2$: costs $3 \cdot 2^{d-1}$



- Glueing solutions: costs $r \cdot 2^{d-1}$

Computational Results

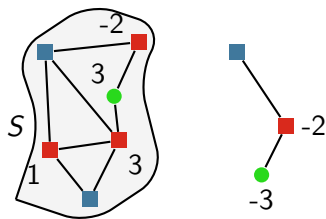
- instances: hypercubes, random r in each scenario
- Cplex 12.3, CS2 code by Goldberg for CP
- Intel(R) Core(TM) i7 CPU @ 1.73 GHz, 64 bit,
- time limit of 7200 sec.
- average values

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dim.	CP		RND _{init}		$T = \infty$		$T = 25$	
	time	%gap	time	%gap	time	%gap	time	%gap
6d	0.06s	16.10	1533.59s	0.25	21.82s	1.02	16.29	1.02
7d	0.24s	25.78	7200.00s	10.70	3003.73s	2.13	448.77s	4.02

New IP-formulation: Cut-Set-Inequalities

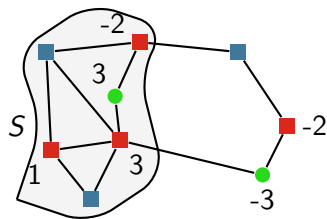


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$$\sum_{\{u,v\} \in \delta(S)} u_{u,v} \geq \max_{q=1,\dots,K} \left| \sum_{v \in S} b_v^q \right| \quad \text{for all } S \subseteq V$$

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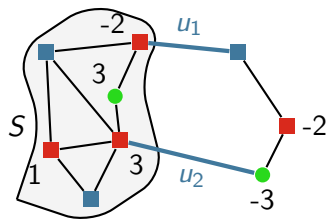


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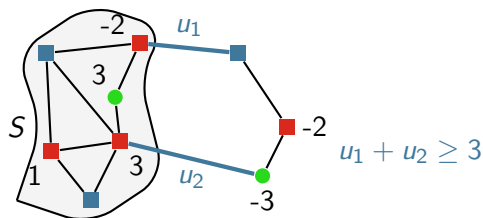


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Results: Branch-and-Cut

- Intel(R) Xeon(TM) 5680 @3.33Ghz CPU, 64bit
- time limit of 7200s
- CPLEX 12.1, ABACUS 3.2 (beta)

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Instances

- d -dimensional hypercubes
- terminal placement as before, random demands

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Results

- 2d, 3d, 4d: Solved to optimality in $< 1s$
- 5d: 7/10 solved to optimality, 3.0% avg. gap
- 6d: 2/10 solved to optimality, 4.7% avg. gap
- 7d: 9/10 with no bound, 1/10 with 14.7% gap

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Instances

- based on [Altin, Amaldi, Belotti and Pinar 2007]
- used by [Buchheim, Liers, Sanità 2011]

Results: Branch-and-Cut

- Intel(R) Xeon(TM) 5680 @3.33Ghz CPU, 64bit
- time limit of 7200s
- CPLEX 12.1, ABACUS 3.2 (beta)

Instances

- based on [Altin, Amaldi, Belotti and Pinar 2007]
- used by [Buchheim, Liers, Sanità 2011]

Comparison to flow formulation based B&C

- [BLS 2011]: $\approx 94\%$ solved to optimality
- Our approach: $\approx 75\%$ solved to optimality

The end.

